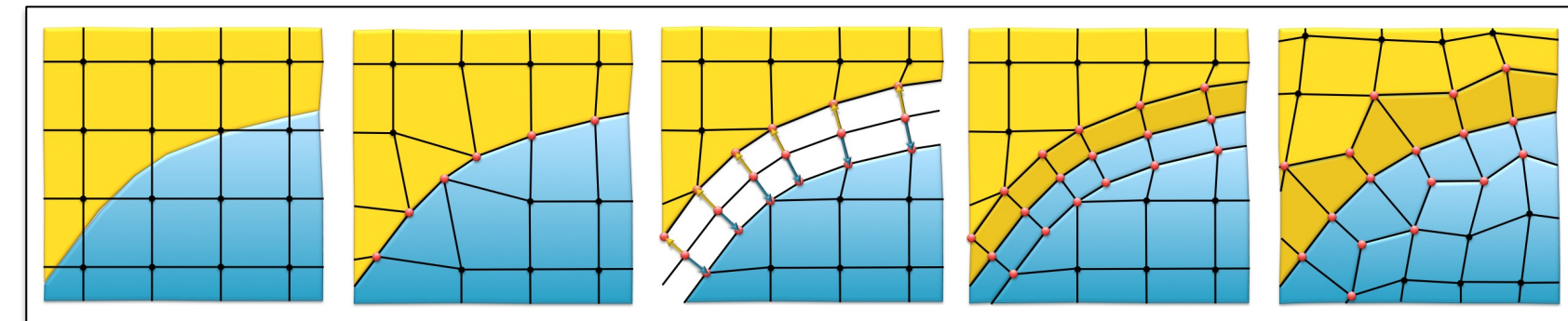


Mesh Optimization in Sculpt

Mesh Optimization is critical to grid based hex meshing tools such as Sandia's Sculpt tool. Work was accomplished this year (FY15) to improve overall success of Sculpt by dramatically increasing minimum mesh quality through a new procedure for parallel smoothing. It incorporates Laplacian and Optimization smoothing but adds damping and parallel coloring to achieve improved results.

Sculpt Meshing Procedure



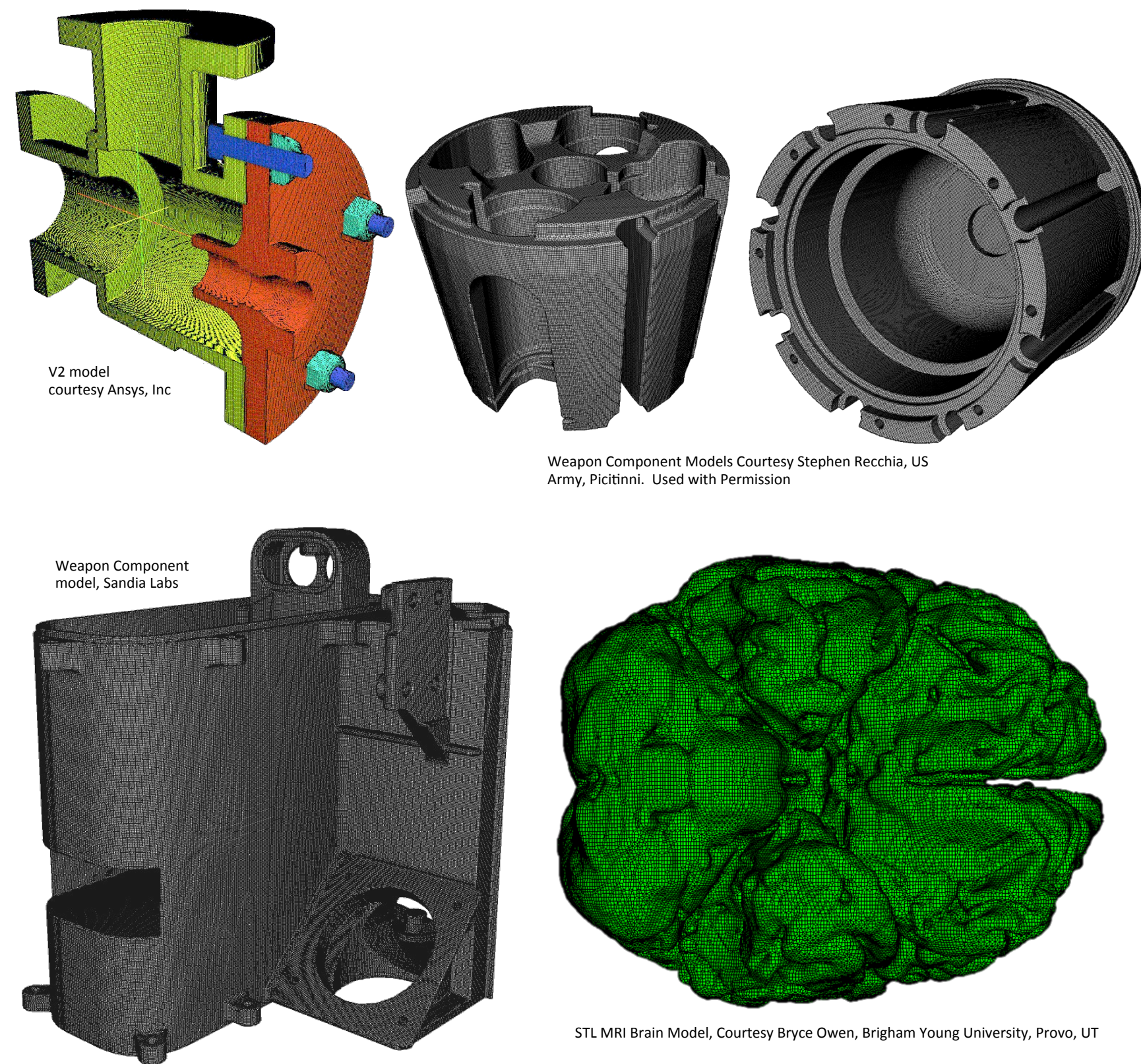
Overlay
Cartesian
Grid on
Geometry

Nodes
projected to
interfaces

Nodes
duplicated at
interfaces and
moved
orthogonally

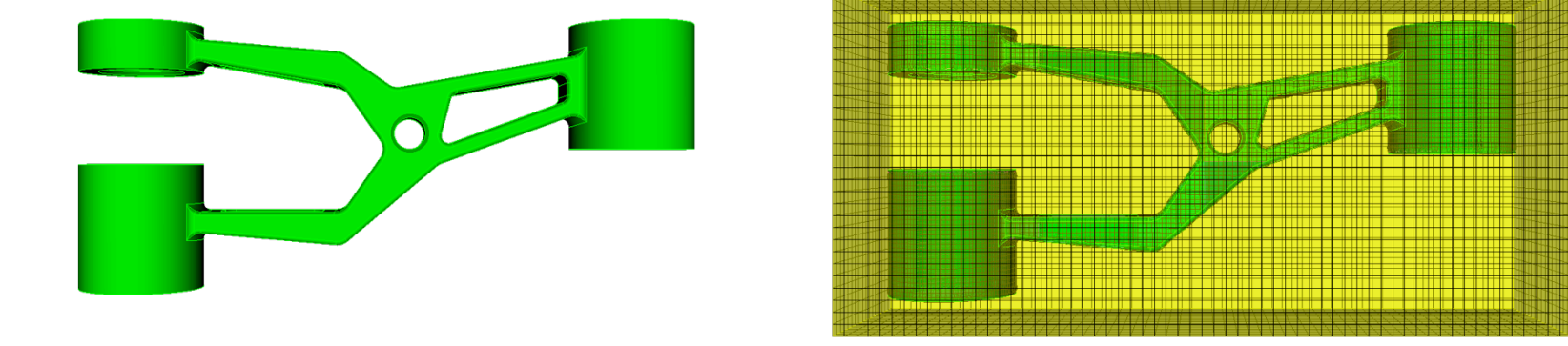
Layers of hexes
created at
interfaces

Smoothing
performed



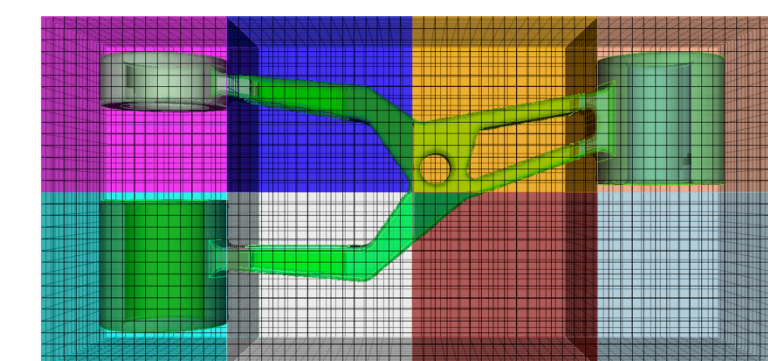
Parallel Meshing in Sculpt

An overlay Cartesian grid is distributed among processors and a hex mesh is independently generated on each processor for a subset of the Cartesian domain. MPI is used for communication between neighboring processors to ensure continuity across processor boundaries. The same mesh will be generated regardless of the number of processors

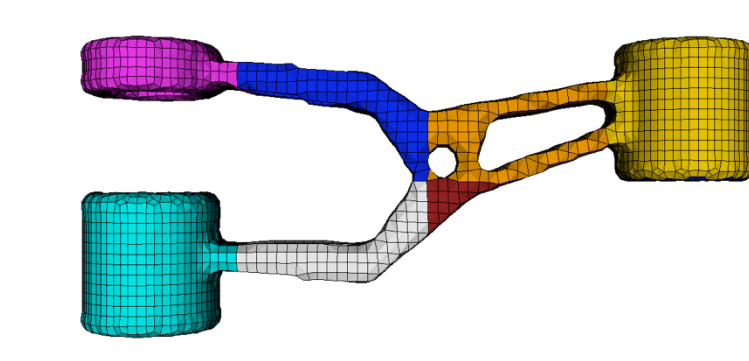


CAD geometry

Global overlay Cartesian grid



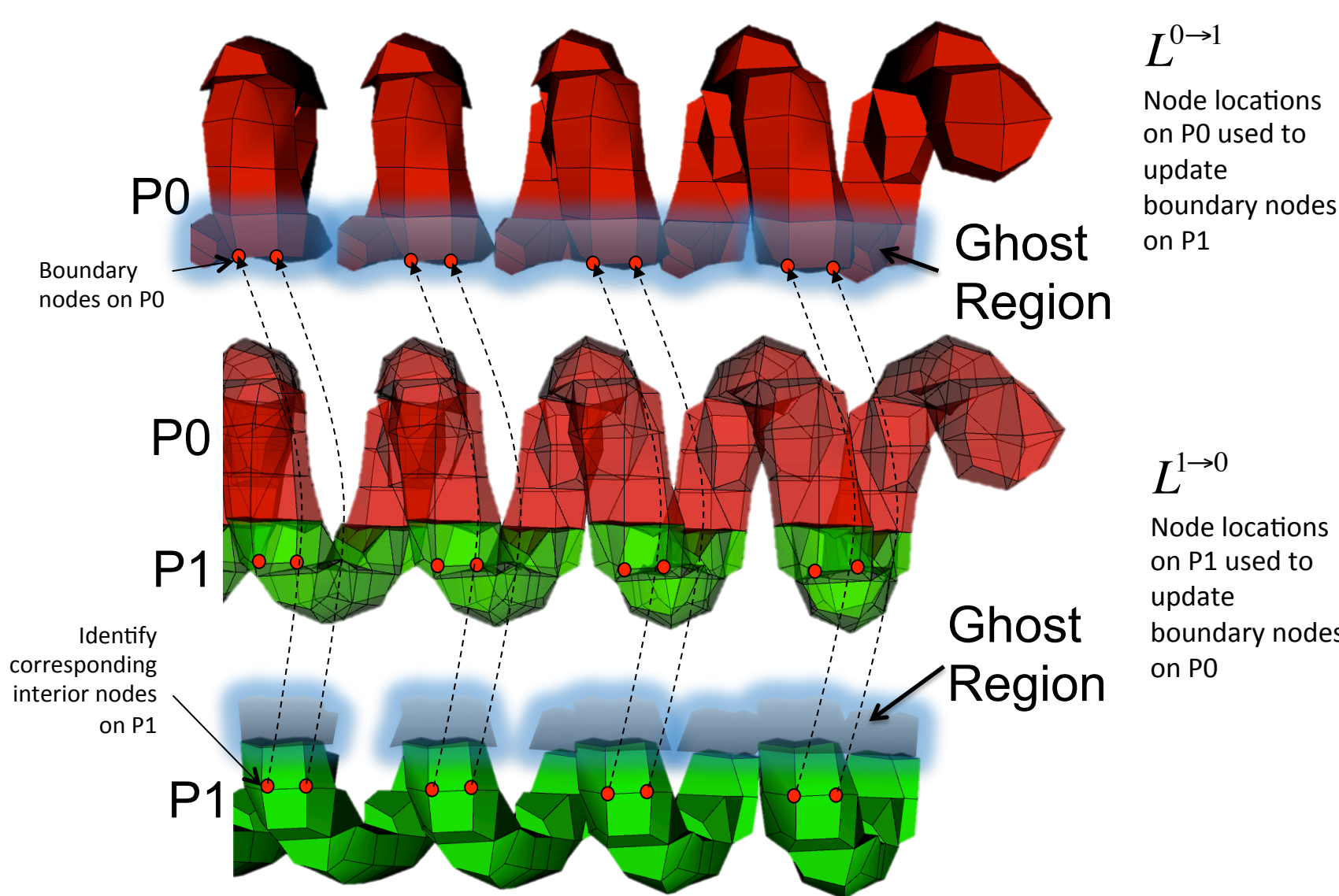
Cartesian grid decomposed and
distributed amongst many processors



Each processor independently meshes
its portion of Cartesian grid

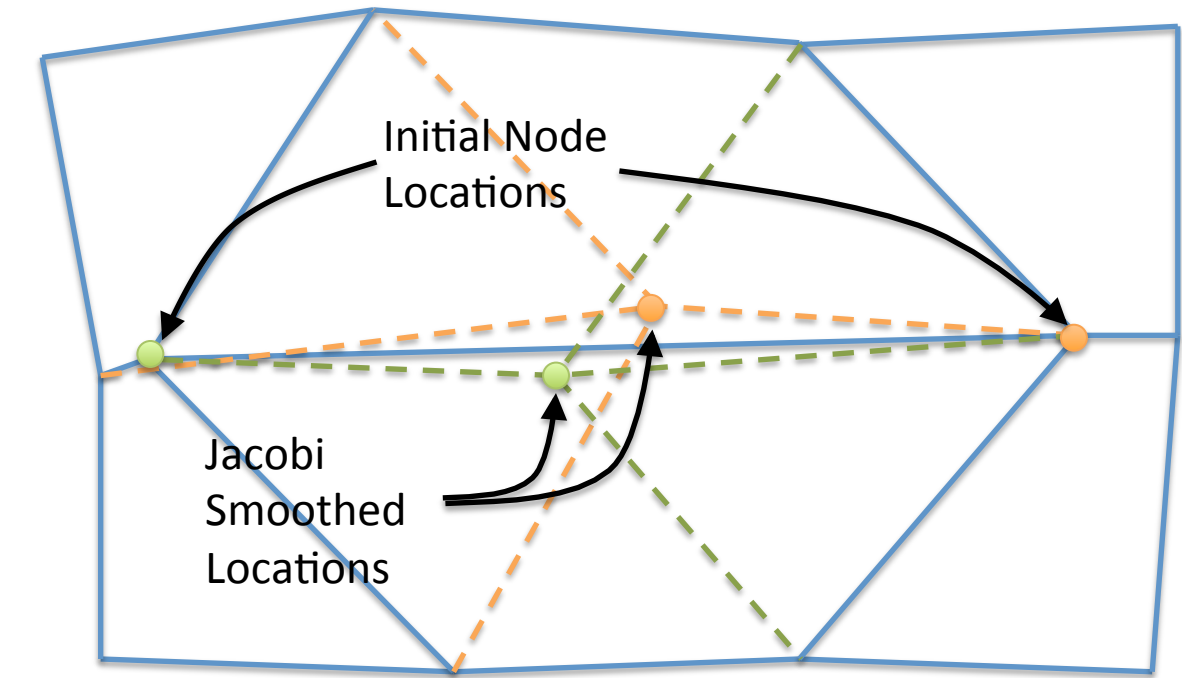
Parallel Smoothing

Ghosted elements and nodes are established and used to facilitate efficient MPI communication following each Jacobi iteration.

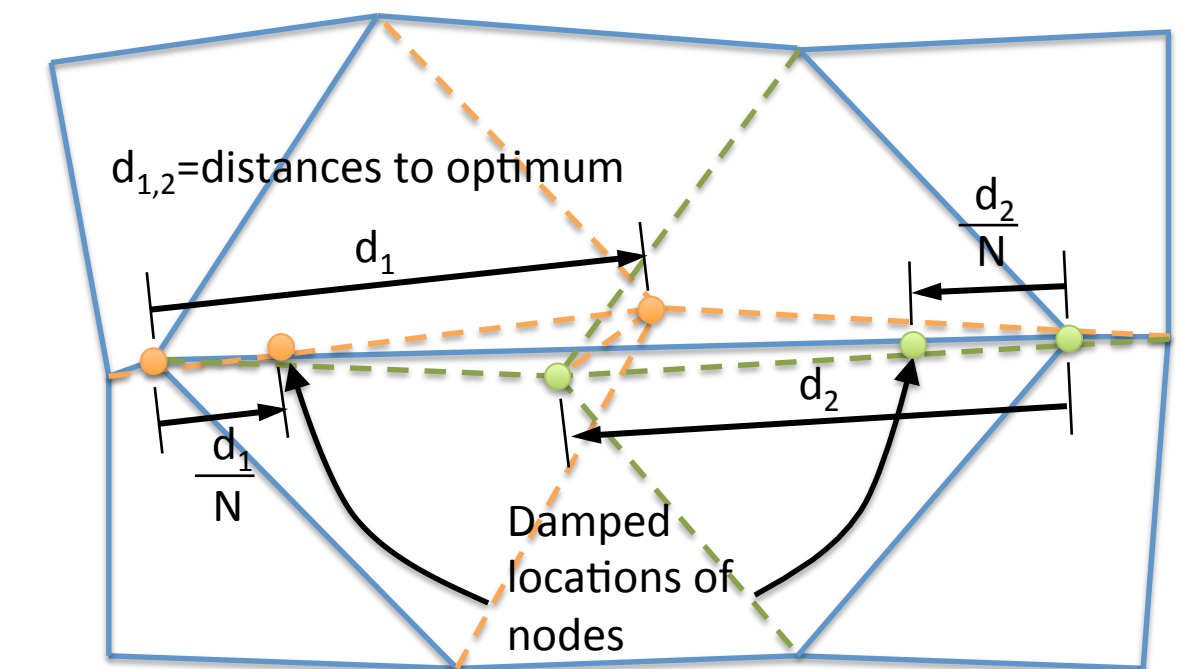


Damping

With Jacobi optimization smoothing it is common to get inverted elements following one or two iterations that are normally resolved with additional iterations. However there are cases that can oscillate and not allow for improvement. Smooth damping is employed to slow convergence avoiding inversions.



Jacobi Smoothing
can result in inverted
elements

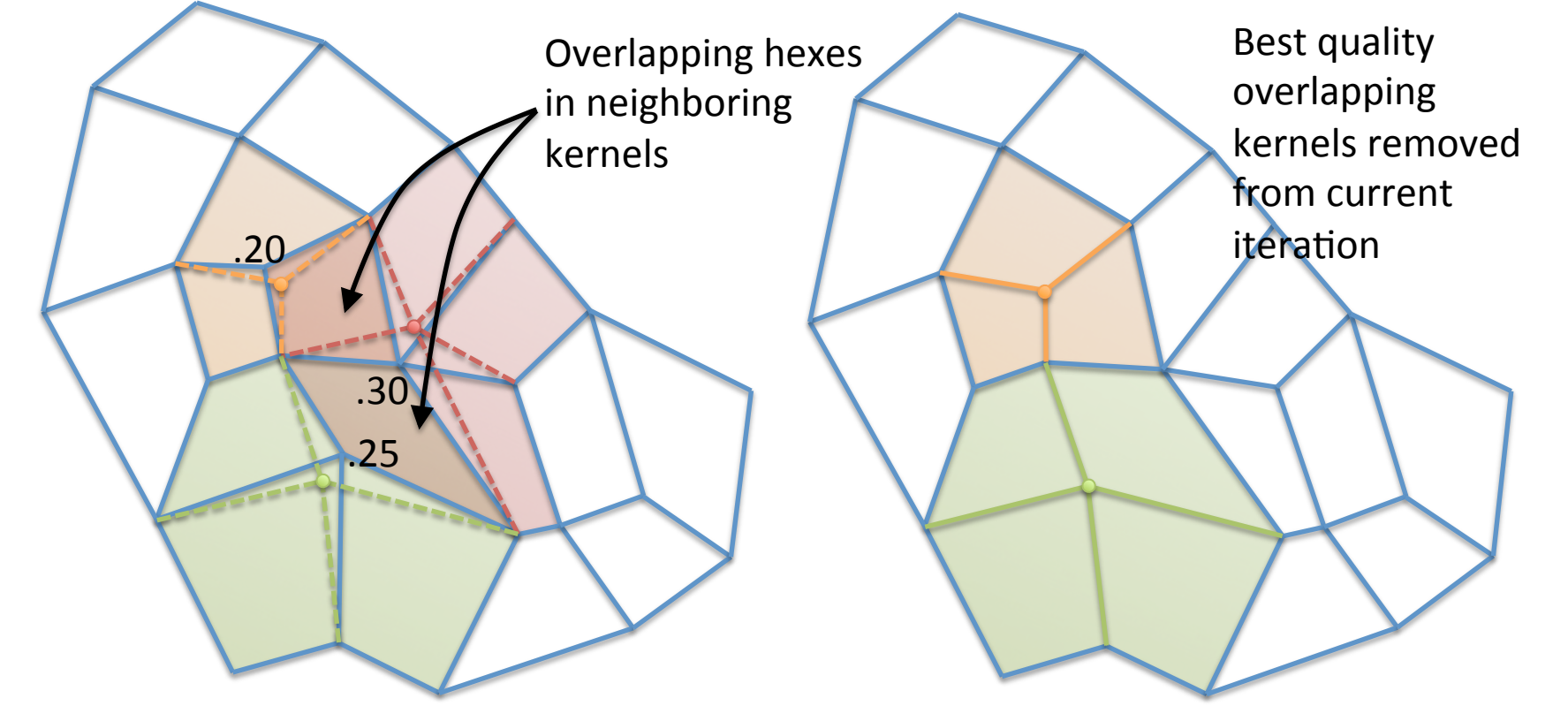


Damping limits the
distance a node can
move for a given
iteration

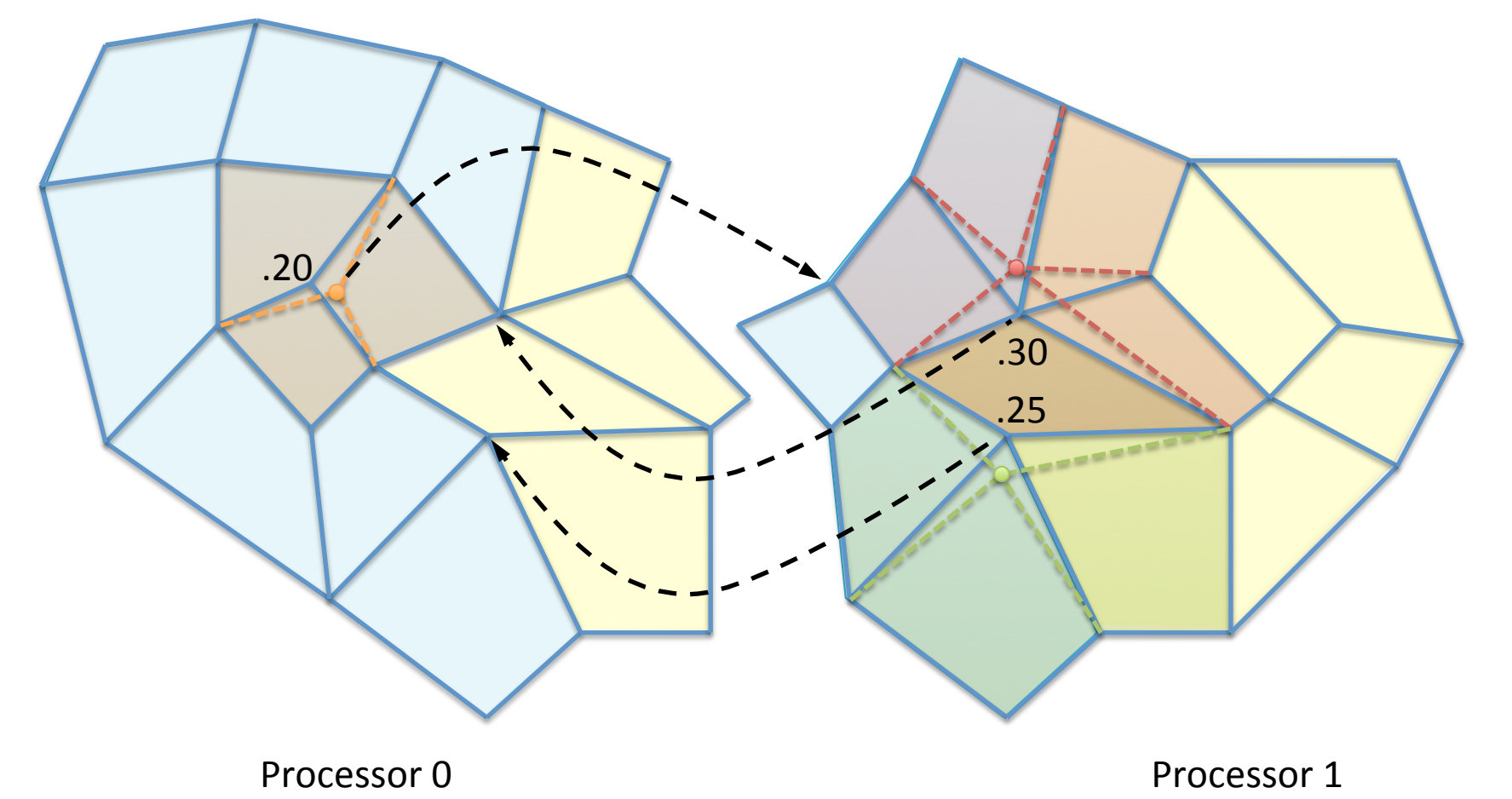
N =
number of remaining
smoothing iterations

Parallel Coloring

The coloring algorithm will attempt to isolate kernels of hexes surrounding a node so that kernels do not overlap. Selection of kernels is ordered based upon minimum scaled Jacobian at the node. For each Jacobi iteration only non-overlapping kernels of hexes are used.



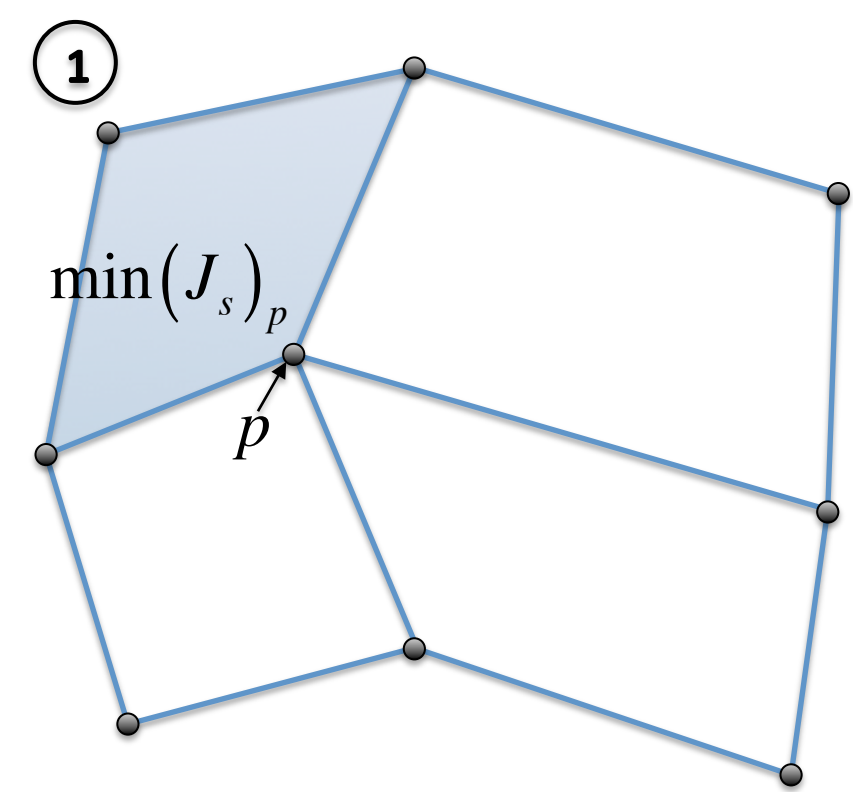
For parallel, master nodes must communicate with their ghosted (slave) nodes the minimum scaled Jacobian of their surrounding hexes. This ensures each processor consistently selects the same hex kernels for smoothing.



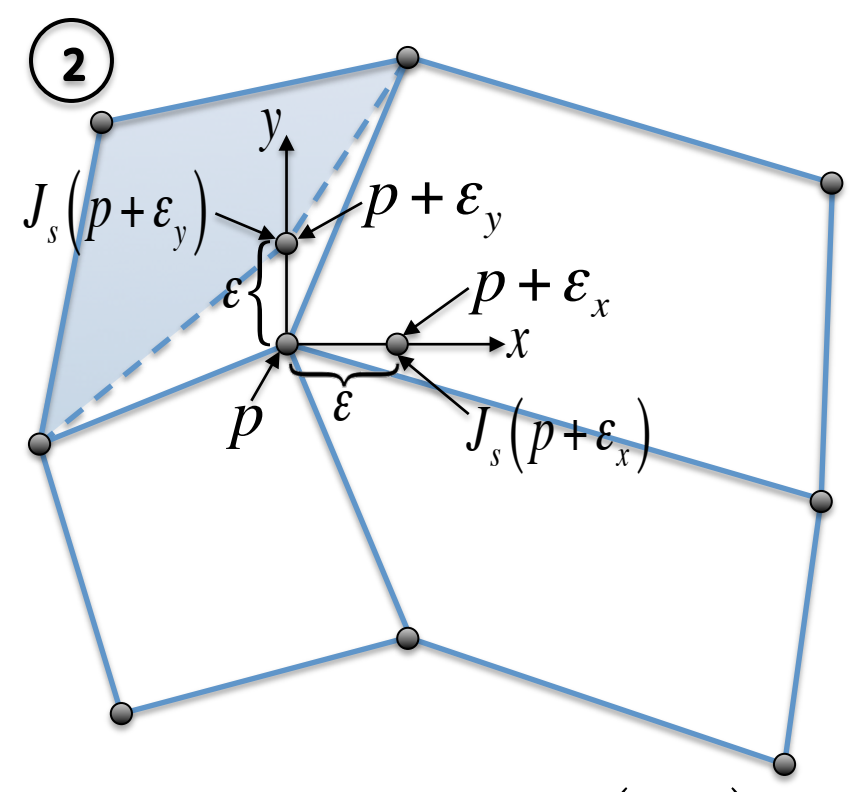
MPI communication of min Scaled Jacobian at node between neighbor processors

Node Optimization

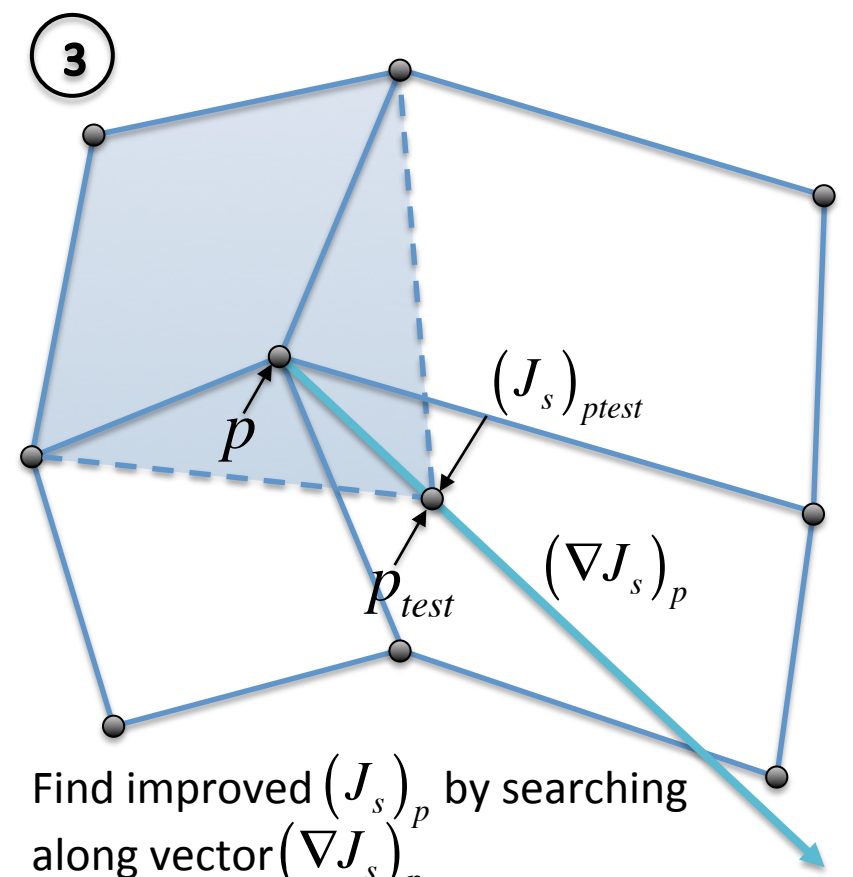
A combined Laplacian and Optimization smoothing procedure is used. Following a fixed number of Laplacian iterations, Optimization is run until a minimum Scaled Jacobian is achieved.



Compute minimum scaled Jacobian, $(J_s)_p$,
of node p in all attached hexes



Compute numerical gradient $(\nabla J_s)_p$



Find improved $(J_s)_p$ by searching
along vector $(\nabla J_s)_p$

Procedure repeated until minimum J_s
exceeds 0.2 or maximum iterations
reached.

$$(J_s)_I = \det \{ \hat{E}_i \hat{E}_j \hat{E}_k \}^T$$

$$J_s = \min ((J_s)_I, I = 0, 1, \dots, 7)$$

Scaled Jacobian Definition

$$(\nabla J_s)_{p_j} = \left\{ \frac{J_s(p+\epsilon_x) - J_s(p)}{\epsilon} \right\}$$

$$(\nabla J_s)_{p_k} = \left\{ \frac{J_s(p+\epsilon_y) - J_s(p)}{\epsilon} \right\}$$

Numerical Gradient

The standard scaled Jacobian
definition is modified to account
for a target element size

$$S_f = \text{Target element size}$$

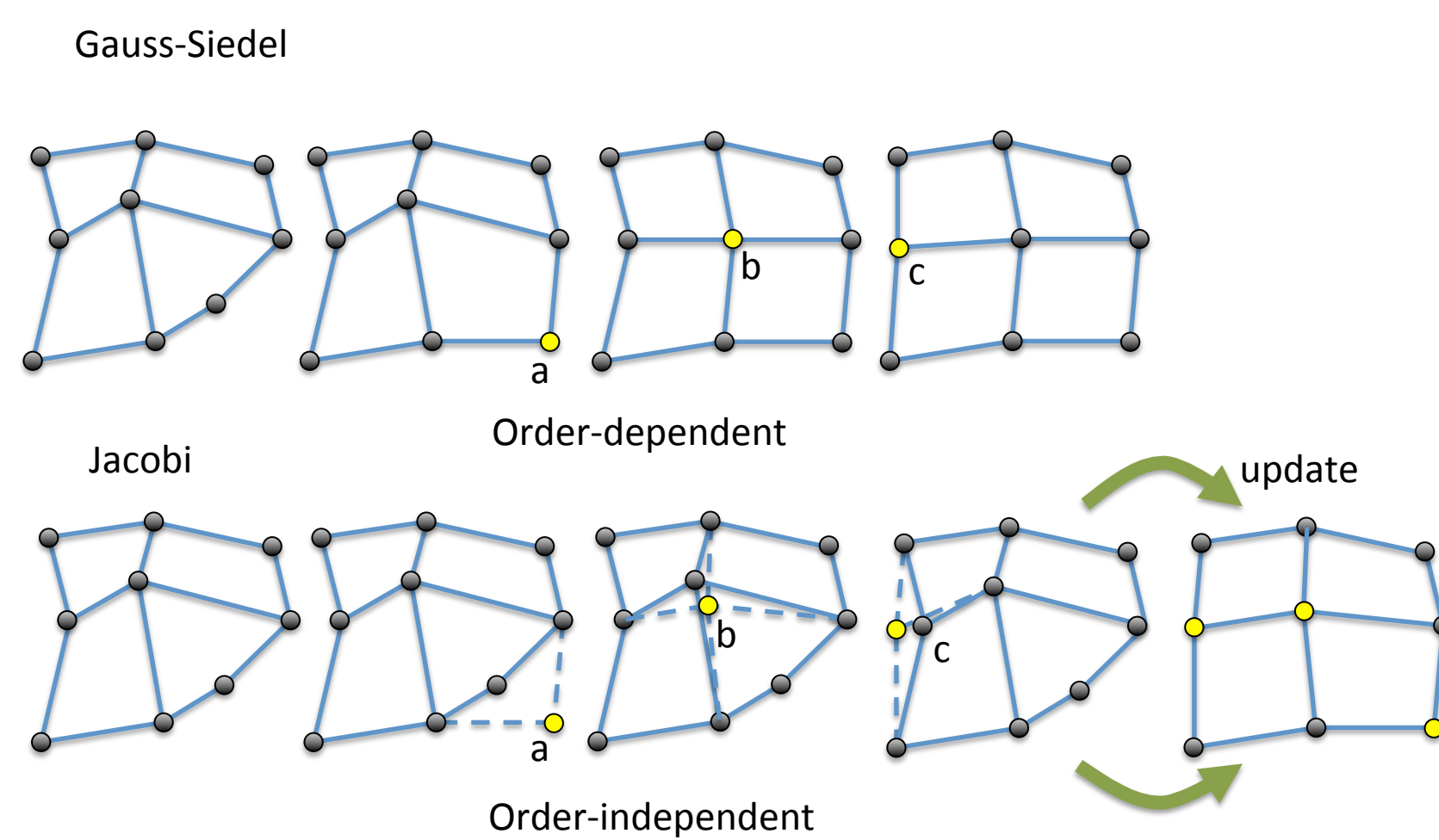
$$(J_s)_I = S_f \det \{ \hat{E}_i \hat{E}_j \hat{E}_k \}^T$$

$$S_f = \left\{ \begin{array}{l} e_s \leq S_t, \frac{e_s}{S_t} \\ e_s > S_t, \frac{S_t}{e_s} \end{array} \right\}$$

$$e_s = \min (\|E_i\|, \|E_j\|, \|E_k\|)$$

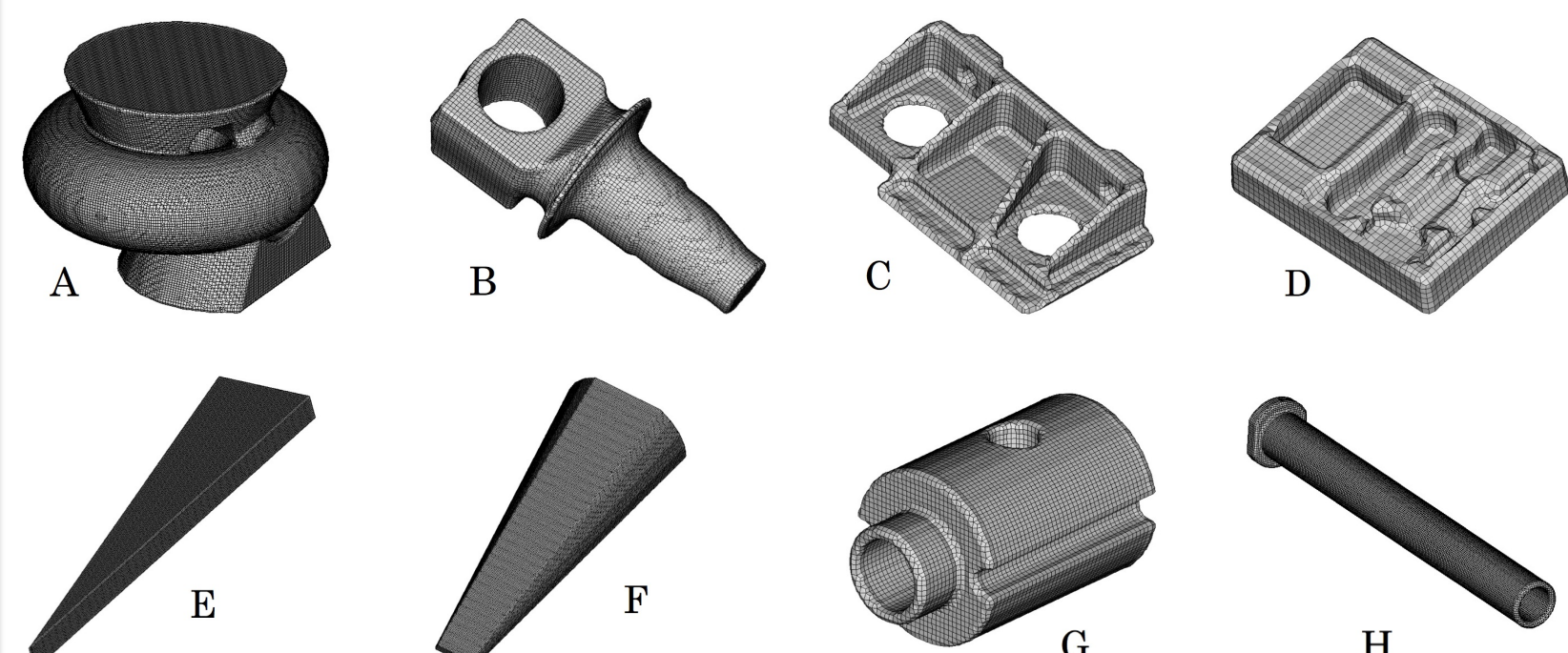
Smoothing Strategies

For serial applications, where order of operations is normally not important, a Gauss-Seidel approach is used. In order to maintain parallel consistency we use a Jacobi-based smoothing procedure.



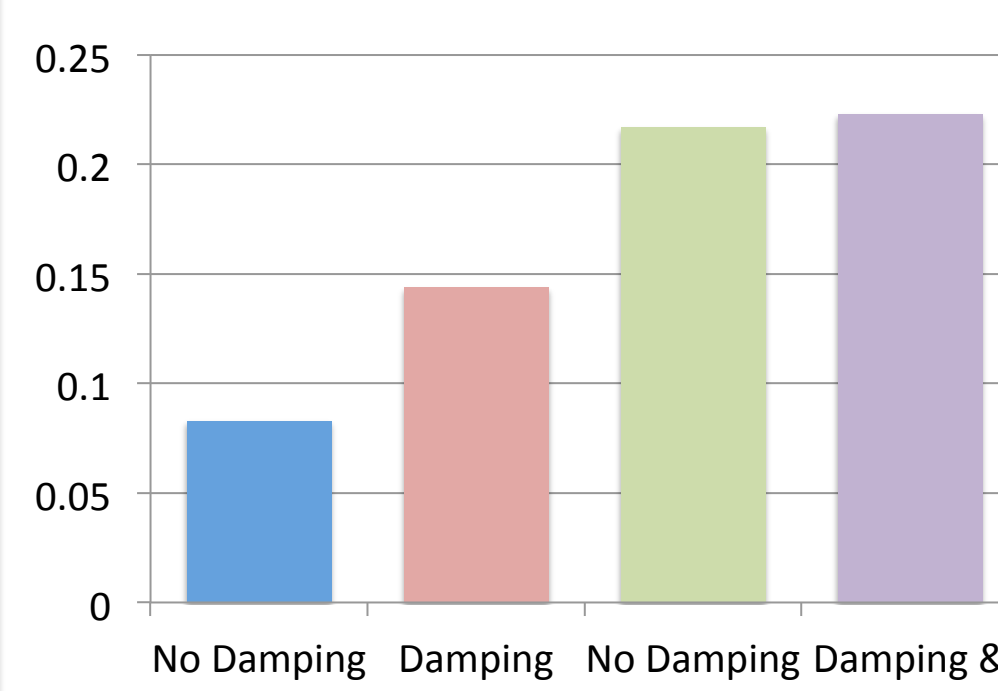
Sculpt Smoothing Comparison

Sculpt's nightly test suite includes a set of 52 single part CAD models. These were used in a comparison study of before and after new smoothing methods were employed.

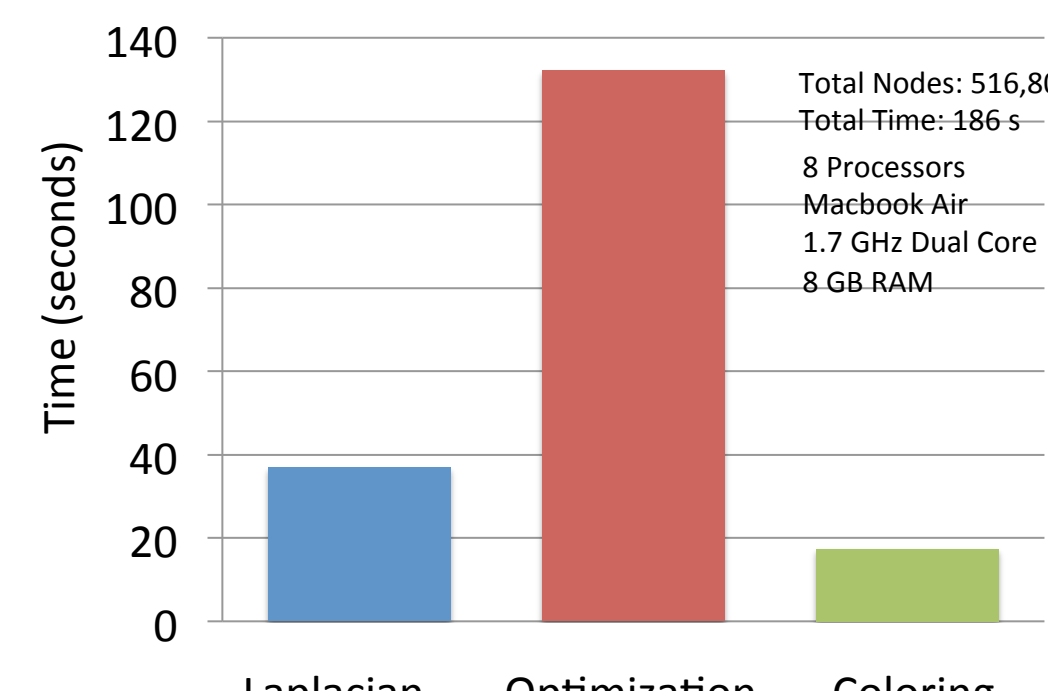


Examples of Test Suite Models: 52 Single Part CAD Models

Average Minimum Mesh Quality



Total Time in Smoothing



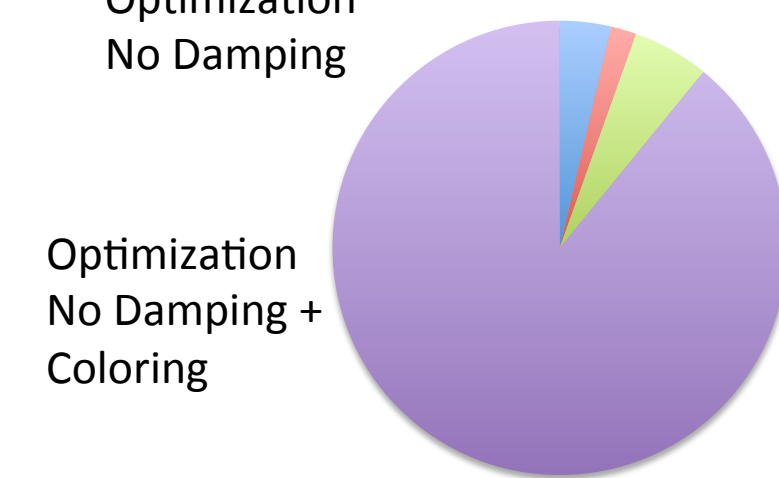
Minimum Mesh Quality

Percent of 52 CAD models whose minimum scaled Jacobian fell within range:

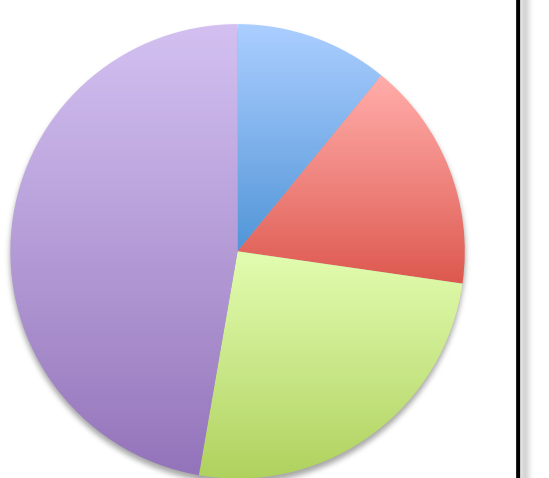
min SJ < 0.0
0.0 < min SJ < 0.1
0.1 < min SJ < 0.2
min SJ > 0.2



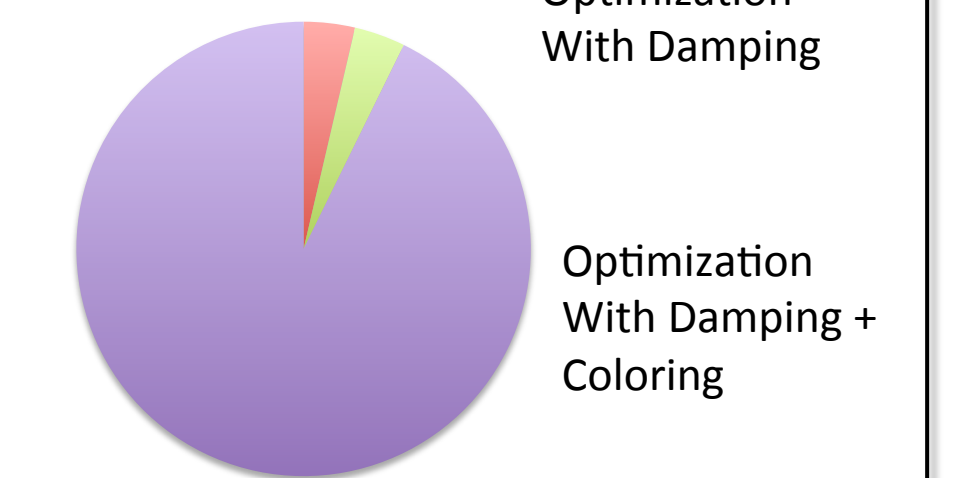
Optimization
No Damping



Optimization
No Damping +
Coloring



Optimization
With Damping



Optimization
With Damping +
Coloring

Sculpt Smoothing Procedure

